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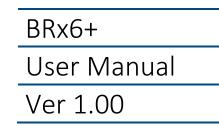






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Environmental

Temperature – operating -30°C to +60°C Temperature – storage -40°C to +80°C Humidity MIL-STD-810F Method 5-7.4 Vibration MIL-STD- 810FG Method. 514.6E-1 Loose cargo MIL-STD- 810F FIG. 514.5C-5

Regulatory Compliance CE Compliance

- IEC 60950-1: 2005
- EN 301 113-1 / EN 301 113-2
- EN 301 489-1 v1.9.2
- EN301 489-3v1.6.1
- EN301 489-7v1.3.1
- EN 301489-17v2.2.1
- EN301 489-24v1.5.1
- EN55022:2010
- EN55024:2010
- EN 300440-1 v1.6.1 / EN 300440-2 v1.4.1
- EN 300 328 V1.9.1
- EN 301 511 v9.0.2
- EN 301 908-1 v6.2.1 / EN 301 908-2 v6.2.1

FCC Compliance

- FCC Part 15, Subpart B
- FCC Part 15, Subpart C :2015
- FCC Part 15, Subpart C:2014
- FCC Part2
- FCC Part22H
- FCC Part24E

IC Compliance

- ICES-003:2012 Issue5
- RSS-247 Issue 1
- RSS-GEN Issue 4
- RSS 132 Issue 3
- RSS 133 Issue 6

Certifications

BRX6+ UHF

- Model: BRX6+UHF
- FCC ID:ZC8BRX6+UHF
- IC:9586A-BRX6+UHF

BRX6+ Non-UHF

- Model: BRX6+Network
- FCC ID:ZC8BRX6+Network
- IC: 9586A-BRX6+Network

AWARNING: If your BRX6+ is equipped with a 400 MHz radio you may be required to obtain a valid radio license for your jurisdiction. Only set the radio to the frequency and power you are licensed to use at your location.



USA- Federal Communication Commission (FCC)

Radio frequency radiation exposure Information:

This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment. GSM Mode

• When using the GSM to receive correction data, this equipment should be installed and operated with a minimum distance of 20 cm between the radiator and your body.

UHF Radio Mode

• When using the 400 MHz radio, M3-TR4 from Satel[™], this equipment should be installed and operated with a minimum distance of 24cm.

This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter. Modifications not expressly approved by Hemisphere GNSS could void the user's authority to operate the equipment. This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation.

This equipment generates, uses, and can radiate radio frequency energy. If not installed and used in accordance with the instructions, it may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation.

If this equipment does cause harmful interference to radio or television reception, which can be determined by tuning the equipment off and on, the user is encouraged to try and correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the distance between the equipment and the receiver.
- Connect the equipment to an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

Any changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

Caution: Exposure to Radio Frequency Radiation.

This device must not be co-located or operating in conjunction with any other antenna or transmitter.

Canada - Industry Canada (IC)

This device complies with RSS 210 of Industry Canada. Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of this device.

L'utilisation de ce dispositif est autorisée seulement aux conditions suivantes: (1) il ne doit pas produire d'interference et (2) l' utilisateur du dispositif doit étre prêt à accepter toute interference radioélectrique reçu, même si celle-ci est susceptible de compromettre le fonctionnement du dispositif.

Caution: Exposure to Radio Frequency Radiation.

The installer of this radio equipment must ensure that the antenna is located or pointed such that it does not emit RF field in excess of Health Canada limits for the general population; consult Safety Code 6, obtainable from Health Canada's website <u>http://www.hc-sc.gc.ca/rpb.</u>

Europe – Declaration of Conformity

This device is in compliance with the essential requirements of the R&TTE Directive 1999/5/EC.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) This device may not cause harmful interference, and

(2) This device must accept any interference received, including interference that may cause undesired operation.

This product complies with the essential requirements and other relevant provisions of Directive 2014/53/EU. The declaration of conformity may be consulted at https://hemispheregnss.com/About-Us/Quality-Commitment



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Patents

Hemisphere GNSS products may be covered by one or more of the following patents:

U.S. Patents	Australia Patents
6111549	68769207400956800038182141112002244539
6397147	71429567429952801837682178332002325645
6469663	71623487437230808519682658262004320401
6501346	7277792746094281023258271194
6539303	7292185768935481389708307535
6549091	7292186780842881402238311696
6711501	7373231783583281744378334804
6744404	738853978857458184050RE41358
6865465	740029479487698190337
Other II C and foreign nations pending	

Other U.S. and foreign patents pending.



1 BRx6+ Overview

Carlson Software's BRx6+ is a multi-GNSS, multi-frequency smart antenna offering robust centimeter-level RTK performance in a variety of applications. The on-board Web user interface (Web UI) allows firmware and features to be configured and managed with any Wi-Fi capable phone or device. With standard Athena RTK technology and optional Atlas functionality, the BRx6+ can operate as a base or rover using the internal radio, modem, or serial out. The BRx6+ supports all constellations, 394 channels, worldwide 4G LTE connectivity, meets IP67 requirements. An internal capacitor allows continuous operation while swapping batteries in the field.



Figure 1: BRx6+

This user guide is intended to introduce the BRx6+ operation to the user along with its many features. We understand there may be questions or comments. If you have a question, we'd like to answer it!

Carlson Technical Support:

- Email: <u>Support@CarlsonSW.com</u>
- Phone: 606-564-5028
- Online: <u>www.CarlsonSW.com/support</u>



1.1 Shipping Case Contents

The BRX6+ is available in two kits, North American (NA) and International (Int'I). Supplementary products sold as "controller/option kits", "accessory kits" are available as well (listed in the <u>Appendix</u>). Contents can change without prior notice. Check the official price list to confirm contents.

Note: Charge your Li-on battery upon receipt of shipment. According to regulations and guidelines, batteries must be shipped charged to less than 30%.



Figure 2: Parts Included

BRX6+ Part Lists

ltem	Main Kits	Part Number	Quantity
1	BRX6+ (NA) Smart Antenna	8030.020.028	1
2	BRX6+ (INT'L) Smart Antenna	8030.020.038	1
3	Internal Battery	8030.058.006	2
4	Battery Charger	8030.060.046	1
5	Battery Charger Adapter	8030.030.046	1
6	BRX6+ Cigarette Lighter Adapter	8030.060.026	1
7	Power Cable (Alligator Clips)	8030.064.036	1
8	Mini Rotary Table	8030.085.001	1
9	Power Cable (Receiver)	8030.064.027	1
10	BRx6+ Serial Cable	8030.064.028	1
11	Quick Release	8030.085.001	1
12	Cell Antenna	8030.043.006	1
13	UHF Antenna Arm	8030.042.100	1
14	UHF External Antenna (TNC)	8030.042.007	1
15	UHF External Antenna (SMA)	8030.042.006	1
16	Tape Measure 12' (not pictured)	8030.080.096	1
17	Carry Case (not pictured)	8030.080.066	1
18	8Gb SD Card (not pictured)		1



1.2 BRx6+ Appearance



Figure 3: BRx6+, Front and Back View



Figure 4: BRx6+, Bottom View



BRx6+ Front Panel 1.3

LED	ICON	Status
Internal UHF Radio / External Data Link LED	DAG	On and blinking: Tx / Rx Data Link Active
	6	Off: Tx / Rx Data Link Inactive
Internal GSM Cell Modem / Network LED	V. 1	On and blinking: Tx / Rx Data Link Active
	Tall	Off: Tx / RX Data Link Inactive
WiFi LED	(î-	On and Solid: WiFi Access Point Active
WIFILED		Off: WiFi Access Point Inactive
	ાગ	On and blinking: Satellite Tracking Active (Every 15s, one
Satellite LED		blink per Sat. used in sol.)
		Off: Satellite Tracking Inactive
Bluetooth LED	•	On and Solid: Active Bluetooth Link to device.
	1	Off: Inactive Bluetooth Link.
	F	On and Blinking: Data Logging active
Logging LED	Ľ	Off: Data Logging inactive

1.3.1 Function and Power Buttons

The Function button 🕅 allows scrolling through the current menu choices while the Power button 🖤 acts as selection confirmation.

1.3.2 Home and Information Screens

Upon boot-up, the receiver will show the home screen, pictured below. The user may access the information screens by pressing the 'FN' button. The screens, shown below, an be scrolled through by pressing the 'FN' button. To return to the home screen, press the 'Power' button.

Π.		ŦG	R
Mo	Sats	00	ST
re	PDOP	0.00	OP
- 6	2017-1	12-20 18:	31

Figure 5: Home Screen

N 0°0	0'00.0 0'00.0 00 m		Int	t.H.: terval ee: 27	: 28		Dat	ffType talink a.: No	: NET	WORK	20.2 5 2 4	de: Ba t: 99 2: 92	*	
LOC RAW	RTK	STAT	LOC	RAW	RTK	STAT	LOC	RAW	RTK	STAT	LOC	RAW	RTK	STAT

Figure 6: Coordinate Information --> File Information --> Current Data Link Status --> Device Status



1.3.3 Receiver Settings Menu

The user may access the general receiver settings by pressing the power button for 0.5 seconds. Once in the receiver settings menu, the user may scroll through the options by pressing the 'FN' button and select that option by pressing the power button.



Figure 7: Receiver Mode, Set, Shutdown, ad Return Options

1.3.4 Receiver Mode Options

Selecting the 'Mode' Icon allows the user to configure the receiver mode. Options are Static, Base, and Rover. The static options allow for the user to select Auto Record or Manual mode; these modes refer to the data logging method while in a GNSS static session.

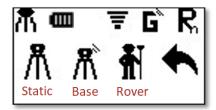


Figure 8: Receiver Mode Options

1.3.5 Receiver RTK Options

Selecting the 'RTK' Icon allows the user to set the RTK wireless device. Options are UHF, GSM, and External UHF.



Figure 9: Receiver RTK Options

1.3.6 Receiver Set Options

Selecting the 'Set' Icon allows the user to configure WiFi, Backlight, and Language settings. The WiFi option allows for the receiver's WiFi to be enabled or disabled. The Backlight option allows for setting the length the display is on before it blacks out; options are 40 seconds, 1 minute, 5 minutes, 30 minutes, or never. The Language option allows the user to select available languages.



Figure 10: Receiver Set Options



1.4 Ports

All ports and connects are located on the bottom of the unit, as shown below.

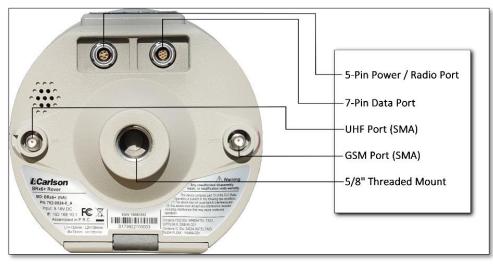


Figure 11: Ports and Connections

Port	Description	
7-Pin Data Port (LEMO)	Data cable for serial or USB	
5-Pin Power / Radio Port (LEMO)	External Power and Radio devices	
GSM Antenna Connector	External GSM Antenna	
UHF Antenna Connector	External UHF Antenna	
Mounting Hole 5/8"	Pole or Tripod Mount	

1.4.1 Power Input Specifications

ltem	Description
Battery	Rechargeable 11.1 V -37.74 Wh
Battery Life	6 hours with one battery and UHF radio in Rx mode
Voltago	9-22V DC external power input with over-voltage
Voltage	protection
Charge Time	7 Hours (typical)



1.4.2 SD / SIM Card Slots

The Micro SD Card and the SIM card are located behind the battery door. Once accessible, the SIM card slot is on the left whereas the Micro SD Card slot is on the right.

The receiver comes with an SD card already installed, the user will need to provide a valid SIM card. To install / remove either card, press in until a snap is heard and it will install / eject the card.

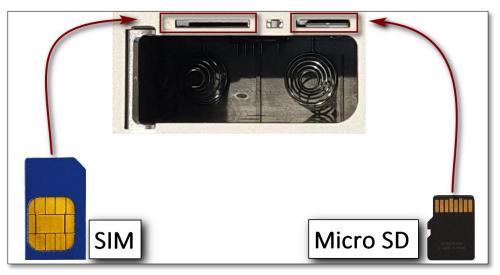


Figure 12: SIM and SD Card Slot Locations



2 BRx6+ Initial Setup

2.1 Install Battery

The BRx6+ allows for one battery (11.1 V - 37.74 Wh) to be installed at a time. When installing the battery, ensure the contact points are facing towards the 'Carlson' logo. Slid the battery into the designated spot until the battery tension bar clicks into place. The projected run time of the battery is 6 hours while operating as a Rover with the internal UHF as the data link.

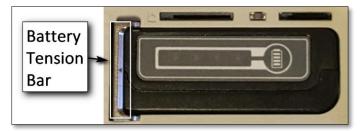


Figure 13: Battery Installation

To remove the battery, push the battery tension bar to the left. The battery should pop-out of the battery compartment. When swapping batteries, the internal capacitor will allow for the BRx6+ to run for \sim 25 seconds – giving the user ample to time to replace a depleted battery with a charged one.

Each battery has a charge level indicator installed on it. Press the battery icon to see the current charge level of the battery.



2.2 Install UHF or GSM Antennas

To install the UHF portion of the BRx6+ antenna, insert the connector end of the UHF antenna and rotate clockwise to secure the antenna to the receiver. To install the GSM portion of the BRx6+ antenna, insert the connector end of the GSM antenna and rotate clockwise to secure the antenna to the receiver.

Note: Only one antenna (UHF or GSM) can be connected to the receiver at a time.



Figure 14: Antenna Installation



2.3 Install on a Tribrach

The BRx6+ mounts flush to the tribrach, by securing the 5/8-11" female metal mounting portion to the standard 5/8-11" male portion of the tribrach. Hand-tighten (35-40 in-lbs. of torque) to secure the BRx6+ onto the mount in a clockwise rotation.



Figure 15: Tribrach Installation Parts

2.4 Quick Release Installation

The quick release attaches to the 5/8" bottom mounting portion of the BRx6+. This adapter then connects to the top of a pole mount or the top of the tribrach mount. This design allows the BRx6+ to be removed from either mounting point at a push of a button.



Figure 16: Quick Release



2.5 Install the Antenna Arm

The antenna arm is typically used when the BRx6+ is configured as a base using the internal UHF radio and mounted on a tripod. The antenna arm moves the UHF antenna away from the BRx6+ and has the UHF antenna point up.



Figure 17: BRx6+ with Tribrach on with UHF Antenna Arm

The BRx6+ UHF Antenna arm is found in each BRx6+ receiver kit and consists of two pieces, the antenna arm an the UHF antenna.

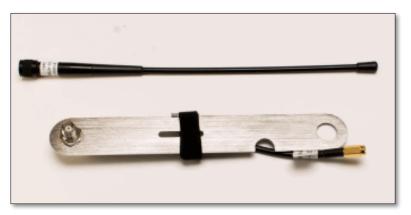


Figure 18: UHF Antenna Arm Kit



2.6 Install on a Range Pole

Using the standard 5/8-11" mount on the bottom of the receiver, the unit can be secured to a field standard 5/8-11" range pole. The receiver should be placed carefully on the range pole, to ensure cross-threading does not occur. Hand tighten (35-40 in-lbs of torque) to secure the unit.



Figure 19: Range Pole Installation

2.7 Connect to an External Power Source

To connect the receiver to an external power source, use the 5-pin Lemo external power cable (054-0171-0). The receiver can be powered from a 9 - 24VDC power supply.



Figure 20: External Power Cable



2.8 Connect to an External Device

The serial cable is available for troubleshooting, debugging, and USB log downloads.



Figure 21: Serial Cable

2.9 Powering On / Off

To power on the receiver, press the 'Power' button for 1 second. The receiver will power up and beep three times when complete. To power off the receiver, press the 'Power' button for 0.5 seconds to activate the Main Menu Screen. From this screen, press the 'FN' key to scroll through the options until the 'Power' Icon is highlighted. Press the 'Power' button to confirm this decision and power off the receiver.

2.10 Reset

The BRx6+ has a reset button located between the Micro SD card and SIM card slots. The reset button will power down the receiver and automatically restart the unit.

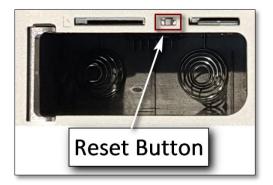


Figure 22: Reset Button Location



3 BRx6+ Key Features

3.1 Navigation Accuracy

Navigation Performance	Horizontal (m)	Vertical (m)
RTK	0.008m + 1ppm	0.015m + 1ppm
Static (long occupation)	0.003m + 0.1ppm	0.0035m + 0.4ppm
Static (rapid occupation)	0.003m + 0.5ppm	0.005m + 0.5ppm
L-Band (Atlas)	0.08m	0.16m
SBAS (WAAS)	0.3m	0.6m
Autonomous, no SA	1.2m	2.4m

3.2 Athena RTK

Athena RTK (<u>Real Time K</u>inematic) technology is available on Eclipse-based GNSS receivers. Athena RTK requires the use of two separate receivers: a stationary base station (primary receiver) that broadcasts corrections over a wireless link to the rover (secondary receiver). The localized corrections are processed on the rover to achieve superior accuracy and repeatability. Performance testing has shown positioning accuracy at the centimeter level.

Athena RTK has the following benefits:

- Improved Initialization time Performing initializations in less than15 seconds at better than 99.9% of the time
- Robustness in difficult operating environments Extremely high productivity under the most aggressive of geographic and landscape oriented environments
- Performance on long baselines Industry-leading position stability for long baseline applications

3.3 SureFix RTK Position

In order to provide high fidelity quality indicators to the users, Hemisphere created an additional processor that runs in combination with the RTK engine, called the SureFix processor. The SureFix processor takes several inputs, such as GNSS data, data preprocessing results, and generated RTK solutions. The SureFix processor takes all available information and, by using functional and stochastic analysis methods, determines the quality of the current RTK engine solution. These are shown as "SureFix quality indicators". The SureFix indicators are then combined with the RTK solution before being provided to the user. At the end of the process, the user has access to high fidelity information about the quality of the RTK solution.

3.4 Atlas L-Band

Atlas L-band corrections are available worldwide. With Atlas, the positioning accuracy does not degrade as a function of distance to a base station, as the data content is not composed of a single base station's information, but an entire network's information. Atlas L-band is Hemisphere's industry leading correction service, which can be added as a subscription. Atlas L- Band has the following benefits:

- Positioning accuracy Competitive positioning accuracies down to 2 cm RMS in certain applications
- Positioning sustainability Cutting edge position quality maintenance in the absence of correction signals, using Hemisphere's patented technology
- Scalable service levels Capable of providing virtually any accuracy, precision and repeatability level in the 2 to 100 cm range
- Convergence time Industry-leading convergence times of 10-40 minutes

BRX6+ is supported by our easy-to-use Atlas Portal (www.atlasgnss.com), which empowers you to update firmware and enable functionality, including Atlas subscriptions for accuracies from meter to sub-decimeter levels.

For more information about Athena RTK, see: https://hemispheregnss.com/Technology For more information about Atlas L-band, see: <u>https://hemispheregnss.com/atlas</u>



3.5 aRTK Position Aiding

aRTK is an innovative feature available in Hemisphere's BRX6+ smart antenna that greatly mitigates the impact of land-based communication instability. Powered by Hemisphere's Atlas L-band system service, aRTK provides an additional layer of communication redundancy to RTK users, assuring that productivity is not impacted by intermittent data connectivity. BRX6+ receives the aRTK augmentation correction data over satellite, while also receiving the land- based RTK correction data. With this, the receiver internally operates with two sources of RTK correction, creating one additional layer of correction redundancy as compared to typical RTK systems. Once that process is established (which takes as less than a few seconds), the receiver is able to operate in the absence of either correction source, or in other words, the receiver is able to continue generating RTK positions in case the land-based RTK correction source becomes unavailable for a period of time.

Note: In order to use aRTK, you are required to change the RTK timeout to: 2700 s. This can be accomplished by following the web UI directions outlined in the Setup and Configuration section of this document.



4 BRx6+ General Operation

4.1 Web UI Operation

In order to first connect to the BRx6+ Web UI, a connection needs to be made the BRx6+ WiFi network. In a phone, tablet, PC, or any other WiFi capable device, search for the BRx6+ WiFi network and connect. The name of the BRx6+ WiFi network will be the serial number of the device.

116	22705003 ernet, open <u>ties</u>		Authentication required http://192.168.10.1 Your connection to this site is not private				
		Disconnect	Username	admin			
	nternet setting s, such as making	15 a connection metered.	Password				
(li.	цу.	(¹)		Log in Cancel			
Wi-Fi	Airplane mode	Mobile hotspot					

Figure 23: Connection made to BRx6+ WiFi Network and Login

The Web UI is located via browser at 192.168.10.1 and the login details are 'admin' and 's321'. Once the login is completed, the Status page of the Web UI will be presented.

Carlson.	BRx6+(NA)	S/N: D173922705003 FW: 1.36.171013 IP: 192.168.10.1 1980-01-06 08:00:00
Status Information Download Management		⊁ Settings C
System Mode: Base [Base Idle] Start	• Current Datalink: UHF	
• Longitude: 0.00000000 °	• Latitude: 0.00000000 °	
• Height: 0.000 m	• Status: Idle	
• Satellites: 0	• PDOP: 0.000	
• HDOP: 0.000	• TDOP: 0.000	
• HRMS: 0.000 m	• VRMS: 0.000 m	
• GNSS Time: 1980-01-06 08:00:00		
support@carlsonsw.com © Copyright 2013 Carlson Software. All Rights Reserved.		

Figure 24: Web UI Status Page

Using Carlson BRx6+ on-board Web UI software, setup for a Base and / or Rover configuration can be made. The general steps will be covered below for Base, Rover, and Static configurations. For more information, please refer to the SurvCE / PC manuals, consult the Carlson Support Website at www.carlsonsw.com/support/support-center or contact the Carlson Support Team at support@carlsonsw.com/support/support-center or contact the Carlson Support Team at support@carlsonsw.com/support/support-center or contact the Carlson Support Team at www.carlsonsw.com/support/support or contact the Carlson Support Team at support@carlsonsw.com support@carlsonsw.com



4.1.1 GNSS Base

Start the BRx6+ and connect to the Web UI (This is done by connecting to the WiFi of the receiver and using 'admin' and 'S321' for username and password). Once connected to the Web UI, click on the 'Settings' button. In the Working Mode tab, select 'Base' for System Mode, and the preferred data link (UHF, Network [GSM], External). For each data link selection, fill out the parameters needed to enable the data link device. Note that the user will need to fill in the selected data link parameters to continue. Scroll down the menu options and fill in the appropriate selections or leave as default (Cutoff Angle, Satellite Selections, etc...). The Base Position has three choices; Single, BaseLink, and Repeat Position. Single allows the receiver to set the position automatically. Be aware that using this selection will set the base location at a unique position for each setup. BaseLink allows for the unit to use Atlas PPP corrections (if service is enabled) and set a location when the preferred convergence precision is reached. Repeat Position allows the user to set the base position by typing in Latitude, Longitude, and Elevation in either Degrees / Minutes / Seconds format or Decimal Degrees format. Once the information is properly entered, click the Save button at the bottom to complete the GNSS Base configuration.

Settings Working Mode	Device Configuration NMEA Message Satellites	Settings Working Mode	Device Configuration NMEA Message Satellites
System Mode	Static Rover Base	Automatically Start Base	● NO ○ YES
Current Datalink	UHF ONEtwork External	Data Type	RTCM3.0
Cutoff Angle	10 •	Site ID	
GPS	• Enable	Pdop Threshold	99.0 [1-99]
GLONASS	enable Oisable	Base Position	 Single BaseLink Repeat Position
Beidou	Enable Isable	Coordinate	Degrees/Minutes/Seconds
Galileo	enable Disable	Base Longitude	-83 ° 45 ° 46.89914 "
SBAS	Enable Disable	Base Latitude	38 38 51.04001
L-Band	Enable Disable	Base Height	135.272 m
aRTK	Enable Isable		

Figure 25: GNSS Base - UHF Datalink Settings



4.1.2 GNSS Rover

Start the BRx6+ and connect to the Web UI (This is done by connecting to the WiFi of the receiver and using 'admin' and 's321' for username and password). Once connected to the Web UI, click on the 'Settings' button. In the Working Mode tab, select 'Rover' for System Mode, and the preferred data link (UHF, Network [GSM], External). For each data link selection, fill out the parameters needed to enable the data link device. Note that the user will need to fill in the selected data link parameters to continue. Once the information is properly entered, click the Save button at the bottom to complete the GNSS Rover configuration.

Settings Working Mode	Device Configuration NMEA Message Satellites	Settings Working Mode	Device Configuration NMEA Message Satellites
System Mode	Static ● Rover ● Base	Athena Log	○ NO ● YES
Current Datalink	UHF ONEtwork External OBluetooth	Point Name	test
Cutoff Apolo	10	Antenna Height	2.000 m
Cutoff Angle	10	Pdop Threshold	99.0 [1-99]
GPS	Enable Oisable		
GLONASS	Inable O Disable	Interval	1HZ T
Beidou	Enable Isable	Radio Channel	1 • 464.55MHz, 12.5kHz Spacing, 1000mW TX
Galileo	enable Obisable	Radio Mode	Satel
SBAS	Enable I Disable	FEC	OFF •
L-Band	Enable Isable		Advanced UHF Settings
aRTK	Enable Isable Isable	Radio Configuration File	Import

Figure 26: GNSS Rover - UHF Datalink Settings



4.1.3 GNSS Static Session

Start the BRx6+ and connect to the Web UI (This is done by connecting to the WiFi of the receiver and using 'admin' and 's321' for username and password). Once connected to the Web UI, click on the 'Settings' button. In the Working Mode tab, select 'Rover' for System Mode, and the preferred data link (UHF, Network [GSM], External). For each data link selection, fill out the parameters needed to enable the data link device. Note that the user will need to fill in the selected data link parameters to continue. Once the information is properly entered, click the Save button at the bottom to complete the GNSS Rover configuration.

Settings Working Mode	Device Configuration NMEA Message Satellites	Settings Working Mode	Device Configuration NMEA Messag	je Satellites
System Mode	Static Rover Base	aRTK	Enable Disable	
Cutoff Angle	10 •	RTK Timeout	30	S
GPS	e Enable	Point Name	Static Session	
GLONASS	Enable O Disable	Antenna Height	2.000	m
Beidou	Enable Disable	Pdop Threshold	99.0	[1-99]
Galileo	e Enable Disable	Interval	THZ •	
SBAS	Enable bisable	Auto Record	NO YES	
L-Band	Enable Disable	External Serial Port Baud	38400 •	
aRTK	Enable Isable	Rate		

Figure 27: GNSS Static Session Settings



4.2 Carlson SurvCE / PC Operation

Using Carlson SurvCE / PC software, setup for a Base and / or Rover configuration can be made. The general steps will be covered below for Base, Rover, and Static configurations. For more information, please refer to the SurvCE / PC manuals, consult the Carlson Support Website at www.carlsonsw.com/support/support-center or contact the Carlson Support Team at support@carlsonsw.com/support/support-center or contact the Carlson Support Team at support@carlsonsw.com/support/support-center or contact the Carlson Support Team at www.carlsonsw.com/support/support/support-center or contact the Carlson Support Team at www.carlsonsw.com/support/support/support or contact the Carlson Support Team at www.carlsonsw.com/support/support/support or contact the Carlson Support Team at www.carlsonsw.com/support/support or contact the Carlson Support Team at www.carlsonsw.com or www.carlsonsw.com or www.carlsonsw.com or <a href="https://www.car

4.2.1 GNSS Base

Begin Carlson SurvCE / PC software and create / resume a job. Once the preferred job settings are selected, click on Equip tab and select GPS Base. In the Current tab, select 'Carlson' as the manufacturer and 'BRx6+' as the model.

🦲 GPS B	ase						\checkmark	X
Current	Comms	Receiver	RTK					
Manufacture	er:	Carlson				•	i	
Model:		BRx6+					·	
Loa	ad	Save	2	[Delete	Defaults		
	au	Jave	-		Delete	Derduits		

Figure 28: GNSS Base - Current Tab

Click on the Comm tab. Depending on the connection type between the data collector and the receiver, select the appropriate connection type. If the connection type is Bluetooth, search and pair the receiver to the data collector. If the connection type is cable, ensure the port settings match the receiver (defaults for the receiver equal the defaults for SurvCE / PC software).

🦲 GPS B	ase		T	\checkmark	X		
Current	Comms	Receiver	RTK				
Туре:	BI	uetooth			·		
BT Type:	10/	indows Mobile			. 0,03		
Device:	XX	××××××××××××			•		

Figure 29: GNSS Base - Comms Tab



Click on the Receiver tab. Select the '[BRX6...]' antenna and enter in the appropriate antenna height.

🦲 GPS E	Base							\checkmark	X
Current	Comms	Receiver	RTK						
Antenna Ty	rpe:	[BRX6		NONE]	Integra		● <u>V</u> ert ○ <u>S</u> lant		
Antenna He	eight:	2		m		Abs. 131.9mm			
Elevation I	Mask:				10			0	
Position R	ate:				1 Hz				•
🗌 Use IM	U								
Audio Mod	le:				Silent				•
	Advanced								
			_	_					

Figure 30: GNSS Base - Receiver Tab

Click on the RTK tab. Select the preferred RTK Device (Internal UHF, Internal GSM, etc...) and configure appropriately.

GPS Base		T\$ 🔽 🚺					
Current Com	ms Receiver RTK						
Device:	Internal UHF						
Network:	None	·					
RTK Port:	Internal Baud: 115200						
Message Type:	ROX						

Figure 31: GNSS Base - RTK Tab



Click on the green check. The software will now present the user with selections to set the base location. If 'Read from GPS' is selected, be aware this this will set the location as approximated by Autonomous precision. Thus, each setup using 'Read from GPS' will be a unique location. Once the appropriate selection is made, the GNSS base setup will complete once the green check is clicked.

🖲 Base	e Configuratio	ion								
From N	ew Position	From Known Position								
	Read From GPS									
	Enter Lat/Lon									
	Enter Grid System Coordinates									

Figure 32: GNSS Base - Base Position



4.2.2 GNSS Rover

Begin Carlson SurvCE / PC software and create / resume a job. Once the preferred job settings are selected, click on Equip tab and select GPS Rover. In the Current tab, select 'Carlson' as the manufacturer and 'BRx6' as the model.

GPS Rover			T 🚺 🔽 🚺
Current Comms	Receiver RTK		
Manufacturer:	Carlson		
Model:	BRx6+		
Load	Save	Delete	Defaults

Figure 33: GNSS Rover - Current Tab

Click on the Comm tab. Depending on the connection type between the data collector and the receiver, select the appropriate connection type. If the connection type is Bluetooth, search and pair the receiver to the data collector. If the connection type is cable, ensure the port settings match the receiver (defaults for the receiver equal the defaults for SurvCE / PC software).

🦲 GPS R	lover					T	\checkmark	X
Current	Comms	Receiver	RTK					
Туре:	BI	uetooth			·			
BT Type:	W	indows Mobile						
Device:	XX	****			•			

Figure 34: GNSS Rover - Comms Tab



Click on the Receiver tab. Select the 'Hems 321' antenna and enter in the appropriate antenna height.

🔍 GPS F	lover				T	\checkmark	X
Current	Comms	Receiver	RTK				
Antenna Ty	pe:	[BRX6	NON	E] Integrated G.	● <u>V</u> ert ○ <u>S</u> lant		
Antenna He	eight:	2	m	Abs. 131.9mm			
Elevation I	Mask:			10		0	
Position Ra	ate:			1 Hz			•
🗌 Use IM	J			🗆 aRTK			
	14 Par	ameter Datum		A	dvanced		

Figure 35: GNSS Rover - Receiver Tab

Click on the RTK tab. Select the preferred RTK Device (Internal UHF, Internal GSM, etc...) and configure appropriately. Click on the green check.



4.2.3 GNSS Static Session

Begin Carlson SurvCE / PC software and create / resume a job. Once the preferred job settings are selected, click on Equip tab and select GPS Rover. In the Current tab, select 'Carlson' as the manufacturer and 'BRx6' as the model.

🦲 GPS R	over						\checkmark	X
Current	Comms	Receiver	RTK					
Manufacture	er:	Carlson					1	
Model:		BRx6+					•	
Loa	ad	Save	2]	Delete	Defaults		

Figure 36: GNSS Static Session - Current Tab

Click on the Comm tab. Depending on the connection type between the data collector and the receiver, select the appropriate connection type. If the connection type is Bluetooth, search and pair the receiver to the data collector. If the connection type is cable, ensure the port settings match the receiver (defaults for the receiver equal the defaults for SurvCE / PC software).

신 GPS F	lover					T	X
Current	Comms	Receiver	RTK				
Туре:	BI	uetooth			•]	
BT Type:	W	indows Mobile					
Device:	xx	****]	

Figure 37: GNSS Static Session - Comms Tab



Click on the Receiver tab. Select the '[BRX6...]' antenna and enter in the appropriate antenna height. The RTK tab is not needed to be configured as the Rover will be logging raw satellite observable data. Click the green check.

over				Ţţ	\checkmark	X
Comms	Receiver	RTK				
e:	[BRX6	NONE	Integrated G	● <u>V</u> ert ○ <u>S</u> lant		
ght:	2	m	Abs. 131.9mm			
ask:			10		0	
te:			1 Hz			-
			aRTK			
14 Par	ameter Datum		,	Advanced		
]			
	Comms be: ght: ask: te:	Comms Receiver pe: [BRX6 ght: 2 ask: te:	Comms Receiver RTK we: [BRX6 NONE ght: 2 m ask:	Comms Receiver RTK ee: [BRX6 NONE] Integrated C 1 ght: 2 m Abs. 131.9mm ask: 10 1 te: 1 aRTK	Comms Receiver RTK we: [BRX6 NONE] Integrated G Image: Stant ght: 2 m Abs. 131.9mm ask: 10 te: 1 Hz Image:	Comms Receiver RTK ee: [BRX6 NONE] Integrated G Image: Orgen to the second

Figure 38: GNSS Static Session - Receiver Tab

Once this is complete, select the 'Log Raw GPS' button within the Survey tab. This will allow for the raw satellite data collection to be configured. Select on the Start/Resume File button and then choose the preferred file attributes and click the green check.

Start New File					X
File Name:			Demo	Manual	
Storage Location:		Internal Mer	nory		
Antenna Height:		2	m	Change Antenna	
Antenna Type:		BRX6	NONE		
Interval:	1.00 seconds		•		

Figure 39: GNSS Static Session - Log Raw Data

The receiver will now be configured to log raw data.



5 BRx6+ Advanced Operation

Carlson.	BRx6+(NA)	S/N: D173922 FW: 1.39, IP: 192.1 2017-12-28 1	.171116 68.10.1
Status Information Downloa	ad Management	✓ Settings	C
Install New Firmware Choose File No file chosen	OUpload File		
GNSS Registration			
GNSS Functionality: 474;0;00/00	/2000;0;OPT=;10Hz;RTK;RAW_DATA;L2_L5;MULTI_GNSS;ATLAS_LBAND		
	Submit		
Security Cld Password: New Password:	Confirm Password: Change		
View Logs			
1. APP Log Download 2. OS Log Download			
Format Internal Disk	ОК		
Self Test	ОК		
Restore Factory Settings	ок		
Reset	ОК		
support@carlsonsw.com © Copyright 2013 Carlson Software	e. All Rights Reserved.		

Figure 40: GNSS Advanced Operation



5.1 Firmware Updates

Within the Management tab of the BRx6+ Web UI, the user may install new firmware. Once the correct software is selected under the 'choose file' button, the 'Upload' button initiates the firmware update procedure. This will restart the BRx6+ (and thus the user must reconnect to the Web UI). Detailed instructions for upgrading the BRx6+ firmware are included within all firmware download packages provided by the Carlson Knowledge Base.

5.2 GNSS Registration

Within the Management tab of the BRx6+ Web UI, the user may view / update current subscriptions. Enter the new authorization code, tap the 'Submit' button and the device will automatically update. Detailed instructions for new or updated subscription codes are available from Carlson Technical Support.

5.3 Web UI Security

The Security field within the Management tab allows the user to enable or disable login Web UI requirements. The user is able to reset or customize a new password for their device by filling in the required fields. The default Web UI username is 'admin' and the default password is 's321'.

5.4 Formatting / Self-Test / Reset

The Format internal disk button allows the user to reformat the internal BRx6+ hard drive. Self-Test allows the user to run the self-test procedure on the BRx6+ to ensure proper operation (Note that GSM will fail if not the current datalink). Reset allows the user to initiate a complete device shut down. The reset will stop any application activity (logging, Bluetooth connection, etc.).



5.1 Satellite Configuration

Within the Settings of the BRx6+ Web UI, the user may augment the satellite tracking. Click on the 'Settings' button and navigate to the 'Satellites' tab to view / change the current satellite tracking configuration.

Settings	Working Mo	ode Dev	vice Configuration	n] [NMEA	Message	Satellites	Settings	5 (Working Mode	Device Co	onfiguration	NMEA	Message	Satellites
							GZU		R2U		C20		E2U	
G9	R		C9		E9		G21		R21		C21		E21	
G10	R1	0	C10		E10		G22		R22		C22		E22	
G11	R1	1	C11		E11		G23		R23		C23		E23	
G12	R1	2	C12		E12		G24		R24		C24		E24	
G13	R1	3	C13		E13		G25				C25		E25	
G14	R1	4	C14		E14		G26				C26		E26	
G15	R1	5	C15		E15		G27				C27		E27	
G16	R1	6	C16		E16		G28				C28		E28	
G17	R1	7	C17		E17		G29				C29		E29	
G18	R1	8	C18		E18		G20	_			C30		E30	
G19	R1	9	C19		E19						0.50			
G20	R2	0	C20		E20		G31						E31	
			C21		E21		G32						E32	
	R2		C22		E22		Select All			Unsel	ect All			
	R2		C23		E23									
525	, RZ	0	023		Save	Cancel							Save	Cancel

Figure 41: Satellites Settings



6 BRx6+ Technical Specifications

6.1 GNSS Receiver

ltem	Description
Receiver type	Multi Frequency GNSS
Channels	394
Positioning modes	RTK, L-Band, DGNSS, SBAS, Autonomous
RTK formats	RTCM (2.3, 3.0, 3.x), CMR, CMR+, ROX
L-Band formats	Atlas H100, Atlas H30, and Atlas H10
Update rate / recording interval	Selectable from 1, 2, 4, 5, 10 Hz. (20 Hz available as upgrade)

6.2 Performance

ltom	Specification				
Item	Horizontal	Vertical			
RTK Performance	8mm + 1ppm	15mm + 1ppm			
Static Performance (long occupation)	3mm + 0.1ppm	3.5mm + 0.4ppm			
Static Performance (rapid occupation)	3mm + 0.5ppm	5mm + 0.5ppm			
L-Band Performance ³	0.08m	0.16m			
SBAS Performance ¹	0.3m	0.6m			
Autonomous no SA ²	1.2m	2.4m			

6.3 Satellite Tracking

ltem	Specification
GPS	L1C/A, L1P, L2P, L2C, L5
GLONASS	G1, G2, P1, P2
BeiDou	B1, B2
QZNSS	L1C, L1CA, L2C, L5
Galileo	E1BC, E5a, E5b
SBAS	MSAS, WAAS, EGNOS, GAGAN

6.4 Communication and Port Specifications

ltem	Description			
	5-pin Lemo connector for external power supply and external radio devices			
Connectors I/O	7-pin Lemo connector for USB OTG connection and a serial port interface			
	2 antenna connectors (internal radio and internal modem)			
	To upgrade this software, manage the status and settings, data download. Connection via smart			
Web UI	phone, tablet or other electric device.			
TTS	Smart voice broadcast system. "Speaking" receiver			
Reference	DTCM 2.0. DTCM 2.2. CMD. CMD. and DOV (Usersionhous mannister)			
Outputs	RTCM 3.0, RTCM 3.2, CMR, CMR+, and ROX (Hemisphere proprietary messaging format)			



6.5 Radio Specifications

Item	Description
Frequency Range	410 – 470 MHz
Channel Spacing	12.5 KHz / 25 KHz
Emitting Power	0.5w / 1w

6.6 Wireless Specifications

ltem	Description
WiFi	Integrated module with internal WiFi antenna 802.11 (B, G, N)
Bluetooth	Bluetooth 2.1 + EDR Integrated Bluetooth (BT) communication module with internal BT antenna

6.7 Cellular Specifications

ltem	Description
Туре	PLS8-E (Int'I)
	4G – Penta Band LTE – 800/900/1800/2100/2600 Mhz – FDD-Band (20,8,3,7,1)
Supported Frequencies	3G – Tri Band UMTS (WCDMA) – 900/1800/2100 Mhz – FDD-Band (8,3,1)
	2G – Dual Band GSM/GPRS/EDGE – 900/1800 Mhz
Туре	PLS8-X (North America)
	4G – Penta Band LTE – 700/700/850/AWS (1700/2100)/1900 – FDD Band (13,17,5,4,2)
Supported Frequencies	3G – Tri Band UMTS (WCDMA) – 850/AWS (1700/2100)/1900 – FDD Band (5, 4,2)
	2G – Quad Band GSM/GPRS/EDGE – 850/900/1800/1900 Mhz

6.8 Power Specifications

ltem	Description
Battery	Rechargeable 11.1 V -37.74 Wh
Battery Life	6 hours with one battery and UHF radio in Rx mode
Voltage	9-22V DC external power input with over-voltage protection
Charge Time	7 Hours (typical)

6.9 Memory Specifications

ltem	Description
SIM Card	Accessible SIM card slot
Memory	Internal 8GB. Accessible through USB and WiFi External Micro SD card slot. Supports up to 64GB.



6.10 Environmental Specifications

ltem	Description	
Operating Temperature	-30°C to 60°C (-22°F to 140°F)	
Storage Temperature	-40°C to 80°C (-22°F to 176°F)	
Water / Dust Proof	IP67	
Shock Resistance	MIL-STD-810G, method 516.6	
Vibration	MIL-STD-810G, method 514.6E-I	
Humidity	Up to 100%	

6.11 Mechanical Specifications

ltem	Description	
Size	14.1 D x 14.0 H (cm) / 5.5 D x 5.5 H (in)	
Weight	<1.38kg / 3.05lbs	
Mounting	5/8" x 11, 55° thread angle, stainless steel insert	
Phase Center Offset	GPS L1 and L2 offset below 2.5mm	
1Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity		

geometry, and ionospheric activity 2Depends on multipath environmen 2Depends also on baseline length 3Requires a subscription

6.12 Radio Modes

Radio Mode	Link Rate	Spacing	Modulation	Scrambling	FEC	
Trimtalk 1	4800 bps	12.5 kHz	- GMSK		Off	
Trimtalk 2	9600 bps	25 kHz			OII	
PC1	9600 bps	25 kHz			On	
PC5	4800 bps	12.5kHz		- On	On	
PC-4FSK	9600 bps	12.5 kHz	4FSK	12.5 kHz	UII	On
PC-4F3N	19200 bps	25 kHz				
Satel 3AS	9600 bps	12.5 kHz			Off / On	
Salei SAS	19200 bps	25 kHz			Off / On	



7 BRx6+ Troubleshooting

The table below provides troubleshooting tips.

Issue	Possible Resolution
	External power is low
	Check charge on external battery and the fuse on the power cable, if applicable.
	Internal power: Check charge on internal battery.
	Check all power cables and pins.
Receiver fails to power	Try other batteries or cables.
	Make sure to hold the power button down for a minimum o fone full second to turn
	on.
	Ensure the battery is installed with contact pointed in the correction direction.
	Check receiver power status.
No data logged	Verify that it is locked to 4 or more GPS satellites.
1.) No communication	Check integrity and connectivity of power and data cable connections.
2.) No valid data	Verify that the baud rate settings match in external device mode.
2.) NO vallu uata	If trying to connect over Bluetooth, ensure Bluetooth module is powered ON and
	device is paired prior to opening the port.
	Verify the messages selected in the output messages in the Web UI match intended
Rando data from Web UI or	selections.
Direct Link mode	Verify the baud rate settings match.
	Potentially, the volume of data requested to be output could be higher than the
	current baud rate supports. Try using a higher baud rate for communications.
	If in "RTK Float", then it is receiving RTK or Atlas corrections.
	If the RTK latency is between 10-15 seconds, these are most likely Atlas corrections.
	If the RTK latency is less than 10-15 seconds, RTK corrections are being received but
	probably will not Fix due to environment.
Mode will not go RTK Fixed	Check base station operation, ensure correction stream is active.
	Verify the settings of the UHF radio at the base and at the rover are exact.
	If using a network, check the Cellular Signal Quality (CSQ) under the information tab
	for cellular reception. CSQ can also be viewed on the display screen by pressing the
	'FN' button.



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10 Appendix

10.1 Accessory Kits

Accessory Kits	Part Number
BRx6+ Serial Cable (5-Pin)	8030.064.028
BRx6+ Power Cable (Alligator Clips)	8030.064.036
BRx6+ Pwr Cbl to Rcvr & DB-9 Serial	8030.064.027
Cell Antenna	8030.043.006
UHF Antenna (SMA)	8030.042.006
400MHz UHF Antenna (TNC)	8030.042.007
Battery (Pair)	8030.058.006
Battery Charger Adapter	8030.060.046
Battery Charger (CH-03)	8030.060.006
Cigarette Lighter Adapter	8030.060.026
Mini Rotary Table	8030.085.001
Quick Release	8030.085.002
BRx6+ External UHF Antenna Bracket Kit	8030.042.100
BRx6+ Carry Case	8030.080.066